# **Technical Data ECHOGRAPH 1095**

**DISPLAY** 

Type of display Colour TFT- LCD, transmissive,

with LED display illumination

Size of display 152.4 mm x 91.44 mm

Resolution 800 x 480 pix, 256 from 262144 colours

Size of A-scan 152 mm x 76.2 mm

Scaling Electronically generated

Scale division Coarse: 10-fold horizontal, 5-fold vertical

Fine subdivision: 25-fold vertical

Image repetition frequency 60 Hz

#### A-SCAN REPRESENTATION AND DIGITIZING

Image refresh frequency 60 Hz

A-scan representation - Normal image (envelope or filled)

- Frozen

Zoom across gate 1 or gate 2
 Across the entire time-base range

RF representation Across the entire time-base range
Rectification Positive, negative, full-wave, without rectifica-

tion (RF)

Suppression Merely adjustable: 0 - 99 % screen height in

steps of 1% (linear)

Zoom Gate range (gate 1/2) to full screen (grid) width

A/D converter 16 bit

Digitising method direct, with A/D converter

Sampling rate 100 MHz

Digitisation sampling error < +/- 0.5% screen height

Response time < 16.7 ms

#### MEASUREMENT RANGES

0.5 - 17760 mm steel Time base range 0.5 – 343.4 mm steel Time base range with TOFD

and B-Scan

Pulse shift

Time base range with signal

averaging Sound velocity Probe delay

Linearity of time base Pulse repetition frequency

(PRF)

Automatic optimization 10 – 700 Hz (Auto high and Auto low), manual (depending on the transmitter) 10 - 5000 Hz [Spike Pulser],

Trigger DAC (option)

Encoder range

Square Wave Pulser, Spike Pulser

10 – 1000 Hz [Square Wave Pulser] internal, 1st echo, external, external 1st echo

Min. distance of the DAC support points:

Uni-directional (negative) Square Wave Pulse

TRANSMITTER

Type of transmitters Shape of transmitter pulse Transmitter setting Specification according to EN 12668-1: td, tr, Vr, V50

SP = Spike Pulser

SWP = Square Wave Pulser SP, 320 V

SP, 80 V SWP, 80 V, 100 ns SWP, 80 V, 3000 ns SWP, 320 V, 50 ns SWP, 320 V, 850 ns

Transmitter pulse voltage V50

Pulse length td

Pulse rise time tr Max Volt after the pulse Vr

Frequency spectrum

Effective output impedance Transmitter damping

0.5 - 1000.5 mm steel

+/- 0.5 % of screen width

 $0 - 650 \, \mu s$ 

200 - 15000 m/s in steps of 1 m/s

0 - 3000 mm in steps of 0.1 mm

Legend: td | tr | Vr | V50

0.3 mm steel 3000 mm max.

36 ns ±10% | < 10 ns | < 12.8 V | 320 V ±10% 57 ns ±10% | < 4 ns | < 3.2 V | 80 V ± 10% 125 ns ±10 % | < 5 ns | < 2.4 V | 80 V ± 10% 3000 ns  $\pm 10 \%$  | < 5 ns | < 2.4 V | 80 V  $\pm 10\%$ 66 ns ±10 % | < 5 ns | < 12.8 V | 320 V ± 10% 850 ns ±10 % | < 5 ns | < 12.8 V | 320 V ± 10%

60 V - 320 V in steps of 1 V

Min.: 31 ns

Max.: 5000 ns (manual, auto depending on the

Min.: 3 ns, Max.: 15 ns

Vr < 4 %

See below: additional data according to

EN 12668-1

< 4 Q

50, 75, 220, 1000\* [Ω]

\*w/o active damping (input resistance

1000 Ohm approx.)

# AMPLIFIER and ATTENUATOR

TOR			
Number of frequency ranges	8 (low pass LP, 2 MHz, 4 MHz, 5 MHz, broad-		
	band BB, 10 MHz, high pass HP, 0.8 MHz -		
	8.0 MHz)		
Nominal frequency ranges	LP:	0.20 - 2.03 MHz	
(- 3 dB)	2 MHz:	1.03 – 3.03 MHz	
	4 MHz:	2.30 - 7.00 MHz	
	5 MHz:	2.10 - 8.10 MHz	
	BB:	1.30 – 14.00 MHz	
	10 MHz:	4.67 – 16.67 MHz	
	HP:	4.9 – 22.50 MHz	
Dosponso	0.8 - 8 MHz: LP:	0.87 – 7.8 MHz fo = 0.64 MHz +/- 5%	
Response	LF.	$\Delta f = 1.83 \text{ MHz} +/- 10\%$	
	2 MHz:	fo = 1.77 MHz +/- 5%	
	Z IVII IZ.	$\Delta f = 2.00 \text{ MHz} + /- 10\%$	
	4 MHz:	fo = 4.01 MHz +/- 5%	
		$\Delta f = 4.70 \text{ MHz +/- } 10\%$	
	5 MHz:	fo = 4.1 MHz +/- 5%	
		$\Delta f = 6.3 \text{ MHz +/- } 10\%$	
	BB:	fo = 4.42 MHz +/- 5%	
		$\Delta f = 12.70 \text{ MHz +/- } 10\%$	
	10 MHz:	fo = 9.2 MHz +/- 5%	
		$\Delta f = 10.30 \text{ MHz +/- } 10\%$	
	HP:	fo = 10.38 MHz +/- 5%	
		$\Delta f = 17.30 \text{ MHz +/- } 10\%$	
	0.8 – 8 MHz:	fo = 2.6 MHz +/- 5%,	
		$\Delta f = 6.93 \text{ MHz +/- } 10\%$	
	111 1110		
Temporal resolution		+/-10 % at 4.4 MHz (broadband	
Temporal resolution	setting BB)	+/-10 % at 4.4 MHz (broadband	
Temporal resolution	setting BB) tA1 = <390 ns		
·	setting BB) tA1 = <390 ns setting BB)	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband	
Temporal resolution  Receiver dynamics	setting BB) tA1 = <390 ns setting BB) LP:	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB $$	
·	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz:	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB	
·	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz:	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB	
·	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz:	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB	
·	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz:	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB	
·	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB:	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB	
·	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz:	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 102 dB	
·	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: 0.8 - 8 MHz: TR Mode:	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 101 dB 102 dB 101 dB 103 dB	
Receiver dynamics	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: 0.8 – 8 MHz: TR Mode: Rmax = 415 Ω	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 101 dB 101 dB 101 dB 103 dB	
Receiver dynamics	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: 0.8 – 8 MHz: TR Mode: Rmax = 415 Ω Cmax = 129 pl	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 101 dB 102 dB 101 dB 103 dB	
Receiver dynamics	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: 0.8 - 8 MHz: TR Mode: Rmax = 415 \( \Omega \) Cmax = 129 pl IR Mode:	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 102 dB 101 dB 103 dB 103 dB 2, Rmin = 455 Ω, F, Cmin = 134 pF (IR)	
Receiver dynamics	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: 0.8 – 8 MHz: TR Mode: Rmax = 415 Ω Cmax = 129 pi IR Mode: Rmax = 120 Ω	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 102 dB 101 dB 103 dB $103 dB$ $105 dB$ $10$	
Receiver dynamics  Equivalent input impedance	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: 0.8 – 8 MHz: TR Mode: Rmax = 415 Ω Cmax = 129 pi IR Mode: Rmax = 120 Ω Cmax = 148 pi	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 102 dB 101 dB 103 dB 103 dB 2, Rmin = 455 Ω, F, Cmin = 134 pF (IR)	
Receiver dynamics  Equivalent input impedance  Equivalent noise level	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: $0.8 - 8$ MHz: TR Mode: Rmax = 415 $\Omega$ Cmax = 129 pl IR Mode: Rmax = 120 $\Omega$ Cmax = 148 pl < 80 nV/ $\sqrt{Hz}$	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 102 dB 101 dB 103 dB 2, Rmin = 455 Ω, F, Cmin = 134 pF (IR) 2, Rmin = 129 Ω, F, Cmin = 147 pF	
Receiver dynamics  Equivalent input impedance  Equivalent noise level Linearity of vertical display	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: $0.8 - 8$ MHz: TR Mode: Rmax = $415 \Omega$ Cmax = $129 \text{ pl}$ IR Mode: Rmax = $120 \Omega$ Cmax = $148 \text{ pl}$ < $80 \text{ nV}/\sqrt{Hz}$ Nominal value	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 102 dB 101 dB 103 dB $103 dB$ $105 dB$ $10$	
Receiver dynamics  Equivalent input impedance  Equivalent noise level Linearity of vertical display Dead time after transmitter	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: $0.8 - 8$ MHz: TR Mode: Rmax = $415 \Omega$ Cmax = $129 \text{ pl}$ IR Mode: Rmax = $120 \Omega$ Cmax = $148 \text{ pl}$ < $80 \text{ nV}/\sqrt{Hz}$ Nominal value <= $1 \mu \text{s}$	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 101 dB 102 dB 101 dB 103 dB 10, Rmin = 455 Ω, F, Cmin = 134 pF (IR) 2, Rmin = 129 Ω, F, Cmin = 147 pF ± 2% screen height	
Receiver dynamics  Equivalent input impedance  Equivalent noise level Linearity of vertical display	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: $0.8 - 8$ MHz: TR Mode: Rmax = 415 $\Omega$ Cmax = 129 pl IR Mode: Rmax = 120 $\Omega$ Cmax = 148 pl < 80 nV/ $\sqrt{Hz}$ Nominal value <= 1 $\mu$ s [measured with	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 102 dB 101 dB 103 dB 10, Rmin = 455 $\Omega$ , F, Cmin = 134 pF (IR) 2, Rmin = 129 $\Omega$ , F, Cmin = 147 pF $\pm$ 2% screen height th the following settings:	
Receiver dynamics  Equivalent input impedance  Equivalent noise level Linearity of vertical display Dead time after transmitter	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: $0.8-8$ MHz: TR Mode: Rmax = 415 $\Omega$ Cmax = 129 pl IR Mode: Rmax = 120 $\Omega$ Cmax = 148 pl < 80 nV/ $\sqrt{Hz}$ Nominal value <= 1 $\mu$ s [measured with Gain: 50 dB, d	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 101 dB 102 dB 101 dB 103 dB 103 dB 103 dB 104 pF (IR) $\Omega$ , Rmin = 455 $\Omega$ , F, Cmin = 134 pF (IR) $\Omega$ , Rmin = 129 $\Omega$ , F, Cmin = 147 pF $\Omega$ screen height the following settings: lamping: 50 Ohm,	
Receiver dynamics  Equivalent input impedance  Equivalent noise level Linearity of vertical display Dead time after transmitter pulse	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: $0.8 - 8$ MHz: TR Mode: Rmax = 415 $\Omega$ Cmax = 129 pl IR Mode: Rmax = 120 $\Omega$ Cmax = 148 pl < 80 nV/ $\sqrt{Hz}$ Nominal value <= 1 $\mu$ s [measured witl Gain: 50 dB, d pulse type: spi	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 101 dB 102 dB 101 dB 103	
Receiver dynamics  Equivalent input impedance  Equivalent noise level Linearity of vertical display Dead time after transmitter	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: $0.8 - 8$ MHz: TR Mode: Rmax = 415 $\Omega$ Cmax = 129 pl IR Mode: Rmax = 120 $\Omega$ Cmax = 148 pl < 80 nV/ $\sqrt{Hz}$ Nominal value <= 1 $\mu$ s [measured with Gain: 50 dB, d pulse type: spi Dynamics range]	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 102 dB 101 dB 103 dB 2, Rmin = 455 Ω, F, Cmin = 134 pF (IR) 2, Rmin = 129 Ω, F, Cmin = 147 pF ± 2% screen height th the following settings: lamping: 50 Ohm, like, volt pulser: 320 V] ge 110 dB	
Receiver dynamics  Equivalent input impedance  Equivalent noise level Linearity of vertical display Dead time after transmitter pulse	setting BB) tA1 = <390 ns setting BB) LP: 2 MHz: 4 MHz: 5 MHz: BB: 10 MHz: HP: $0.8 - 8$ MHz: TR Mode: Rmax = 415 $\Omega$ Cmax = 129 pl IR Mode: Rmax = 120 $\Omega$ Cmax = 148 pl < 80 nV/ $\sqrt{Hz}$ Nominal value <= 1 $\mu$ s [measured witl Gain: 50 dB, d pulse type: spi	+/-10 % at 4.4 MHz (broadband +/-10 % at 4.4 MHz (broadband 102 dB 105 dB 106 dB 106 dB 101 dB 102 dB 101 dB 103 dB 2, Rmin = 455 Ω, F, Cmin = 134 pF (IR) 2, Rmin = 129 Ω, F, Cmin = 147 pF ± 2% screen height th the following settings: lamping: 50 Ohm, like, volt pulser: 320 V] ge 110 dB	

#### MEASURED VALUES

Output of echo amplitude is stated in...

% screen height dBabs in dBuV

DGS/DAC/TCG/JIS/AWS: dBrel (relative to reference echo (line) in dB)

AWS: D = Rating in dB

C = Attenuation B = Reference A = Indication

(following the standard AWS D1.1/D1.1M, only for gate 1)

JIS: class (follow the standard JIS Z3060-

2002, only for gate 1)

DGS: mmFBH in equivalent flat bottom hole

Output of echo transit time is stated in...

mm sound path (with straight probes) mm depth and projection distance or reduced

projection distance (with angle incidence) Resolution: 0.1 mm steel

Output of wall thickness

Distance between trigger points in gate 1 and 2 (the trigger point can be selected from either edge or peak, with RF representation also zero crossing after first edge can be selected). Optional min. or max. wall thickness or

sound velocity.

Resolution 0.01 mm steel, averaging with RF representation can be selected either from 1 to

16 measurements.

#### MONITOR GATES

Number of gates

Response time By pulse repetition frequency Measurement modes Peak, edge, zero crossing Operation modes

Normal or inverted

Range Gate start: 0 – 20000 mm in steps of 0.1 mm Gate width: 0 – 3000 mm in steps of 0.1 mm (independent gates, controlled by skip dis-

tance, gate 2 position follows gate 1)

0 - 250 events Statistical clearing

Switching outputs Level: TTL (5V), low active, ZA = 100 Ohm Response accuracy: +/- 0.5% screen height Switching hysteresis: < 0.5% screen height

Holding time of the switching output: 0.5/PRF with internal triggering, 1 ms with external trig-

gering

Optical indication 3 LEDs on the front panel

Acoustical flaw alarm Duration is 50 ms approx. (re-fresh with PRF) INPUTS and OUTPUTS

Probe connection 2 x Lemo 1

USB interface LEMO-0B, 4 Pin (optionally: adapter cable with

USB Type A)

LEMO-1B, 10 Pin: TTL - level (5 V), low active. Flaw outputs

trigger level 2 V approx.

Synchronising input and output LEMO-1B, 10 Pin: TTL - level (5 V), low active,

trigger level 2 V approx.

Max. PRF = 5 kHz, min. pulse length = 2 µs,

delay between trigger and transmitter

pulse: 50.8 us approx...

max. jitter between trigger and transmitter

pulse: +/- 10 ns

Encoder LEMO-1B, (I/O), 10 pin: square or pulse sig-

TTL level (5 V), power supply via ECHO-

GRAPH 1095 (5 V, max. 200 mA)

External monitor Via standard VGA connector (D-sub-HD 15 pin)

Connector for interface box LEMO 1B, 14 pin

LEMO 1B, (D/A), 14 pin, TTL level (5 V), low:

active, trigger threshold 2 V approx.

Analog outputs LEMO 1B, (D/A), 14 pin: 2.5 Vpo, signal for SH

and wall thickness in gates 1, 2, 3

Impedance: 100.5 Ohm Linearity: error < 4%  $\Delta fg (fgu - fgl) = 21 MHz,$  $fgo = \sqrt{(fgu \times fgl)} = 23.2 \text{ MHz}$ 0 dB to 92 dB ==> noise level < 1V

Monitor position: no influence on the output

Influence of the pulse shape: error < 4% (at

80% SH)

Min. hold time: 2/(pulse repetition frequency)

**MISCELLANEOUS** 

Digital inputs

Linear measuring system

Selectable mm or Inch. Date and time Built-in real time clock

DE, ES, FR, HU, IT, JP, NL, PL, RO, RU, SV, Languages

EN, CN, CZ

The language of the user interface may be se-

lected by the operator.

**STORAGE** 

Memory card SD card slot Memory size 8 GB. SD card Report file CSV format in ASCII

Screenshot BMP format

Types of report Individual report, report of measurem. series, corrosion testing (matrix memory), reference

Data recorder up to 10,000 readings plus important parame-

ters per file, each with assigned A-scan bitmap

file (optionally)

## **POWER SUPPLY**

Mains operation Via power supply unit (input: 100 – 240 V.

50/60 Hz, output: 12 V, 4 A

Permissible operat. temperature: 0 °C to 50 °C

Battery operation Built-in (replaceable) Li-lon batteries

9 h (with standard settings)

Operating time (battery opera-

Data of rechargeable batteries 7.6 Ah - 7.4 V - 56 Wh Charging method for batteries

internally with charger unit (optional external

charger unit available)

4-stage display symbol, about 15 minutes be-Indication of battery capacity

fore low voltage condition (battery operation),

the blue LED will start flashing

If there is a low voltage condition both with Automatic voltage cut-off

mains or battery operation

Stability at voltage changes < ±1% screen height and < ±0.5 % screen

width (with voltage variations within the per-

missible range)

#### PERMISSIBLE AMBIENT CONDITIONS

Permissible operating temper- -10 to +50 °C / -20 to +60 °C

ature (with battery) / storage Dust and humidity

protection class IP65

## **MECHANICS**

Size (HxWxD) 138 mm x 249 mm x 52 mm

w/o rubber holster

149 mm x 262 mm x 54 mm

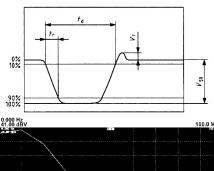
with rubber holster

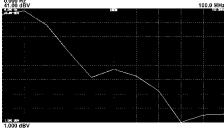
Weight 2.0 kg (with Li-Ion battery and protective

holster)

## ADDITIONAL DATA AC-**CORDING TO EN 12668-1**

Transmitter (definitions)





# Linearity of vertical display

Attenuator	nominal value echo height [%]	-	[%]
+2	100	98 - 100	
+1	90	88 - 92	
0	80	80	
-2	64	62 - 66	
-4	50	48 - 52	
-6	40	38 - 42	
-10	25	23 - 27	
-12	20	18 - 22	
-18	10	8 - 12	
-24	5	3 - 7	

Stability (after warm-up period) Echo height < +/- 2% at temperature changes

Display diffuseness (jitter of the screen display) Accuracy of the calibrated attenuator

Echo position < +/- 0.5% screen width per 10 °C temperature change

Echo height max. 1% screen height, echo position max. +/- 0.2% of screen width

- a) Deviation of fine adjustment: accumulated max. +/- 0.5 dB within a 20 dB interval
- b) Deviation of coarse adjustment: accumulated max. +/- 1 dB within a 60 dB interval

## **REVISION HSITORY**

Rev. A Rev. B Rev. C

#### initial version

digital switching outputs, trigger in/out, encoder analog outputs, digital inputs